

# ASSOCIATION FOR AUTOMATED REASONING

## NEWSLETTER

No. 32

March 1996

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### **From the AAR President, Larry Wos...**

This issue begins with three notes about CADE. The first is a reminder that an important vote on the new bylaws will be held at the 1996 meeting. The second note is about the proposed site for CADE-15. The third is a call for nominations for the prestigious Herbrand award, to be presented at CADE-13. Since CADE is one of the leading conferences in automated deduction, I urge AAR members to read each note most carefully.

Also included in this issue of the *AAR newsletter* is an article by one of our frequent contributors, Li Dafa. Using his ANDP system, he has now produced an automated natural deduction proof of the formalization of the so-called halting problem—a problem that has appeared periodically in our newsletter since 1987.

**A request:** I would like to know whether you, as an AAR member, would prefer to “receive” our newsletter on the Web rather than in paper form. Specifically, we would have *AAR Newsletter* Web pages that would include new articles as they were accepted. We would give hot links to appropriate calls for papers. Please let our editor Gail Pieper (pieper@mcs.anl.gov) know your opinion on this matter.

### **CADE-13 to Hold Vote on New Bylaws**

A vote will be held at the 1996 meeting of CADE to determine whether a new set of bylaws should be adopted for CADE. The vote will be by secret ballot.

So that the voters can make an informed decision, we have put the proposed bylaws and the existing ones on the World Wide Web. See <http://www.cs.albany.edu/~nvm/cade.html>.

### **Proposals for Sites for CADE-15 Solicited**

*Alan Bundy, President, CADE Inc.*

CADE Inc. invites proposals to host the 15th Conference on Automated Deduction (CADE-15). CADE-15 will be held in early to mid-summer 1998 in Europe. Proposals are due by July 1, 1996, and a final decision will be made by September 1, 1996. Proposals will be evaluated in relation to a number of site selection criteria, which include suitability of site and facilities, strength of local automated reasoning research, costs, and availability of local sponsorship. Further details are available on request from the CADE Inc. Secretary, Neil Murray (nvm@cs.albany.edu).

## Nominations for Herbrand Award

*Alan Bundy, President, CADE Inc.*

The Herbrand Award is given by CADE Inc. to honor an person or a group of people for exceptional contributions to the field of automated deduction. Previous awards have been made at CADE-11 to Larry Wos and at CADE-12 to Woody Bledsoe. Nominations for the award can be made at any time to the CADE Inc. president, Alan Bundy (A.Bundy@ed.ac.uk). Nominations should consist of a letter of up to 2000 words from the principal nominator, describing the nominee's contribution, along with letters of up to 2000 words of endorsement from two other seconders. The winner is selected by the CADE Trustees, the current Programme Committee, and the previous winners.

In order to ensure enough time for selection in time for CADE-13, nominations should reach Bundy by April 30. E-mail nominations are preferred.

## Call for Papers

### FMCAD '96

The International Conference on Formal Methods in Computer-Aided Design '96 (FMCAD '96) will be held in Palo Alto, California, on November 6–8, 1996. FMCAD '96 is a forum for presenting state-of-the-art tools and techniques based on formal methods for computer-aided design of hardware. A special focus of this conference will be on the integration of complementary techniques and tools. Specific areas of interest to AAR members include the following.

- New hardware verification techniques based on theorem proving, state exploration, model-checking, and BDDs
- Hybrid approaches that integrate synthesis and verification or different verification techniques
- Formal verification techniques for hardware description languages, such as VHDL, Verilog
- Case studies and application of formal methods in industry

This conference is a sequel in a series of IFIP WG 10.2/10.5 sponsored conferences with similar themes that have been held most recently in 1992 and 1994 under the banner "Theorem Provers in Circuit Design." The intended audience includes workers in the field of hardware verification and synthesis as well as practicing digital designers with an interest in formal methods.

Authors may submit research papers (15 pages) or tutorials (15 pages) in Postscript to [fm-cad96@csl.sri.com](mailto:fm-cad96@csl.sri.com), or may send seven hard-copies to the following (submission deadline is April 15, 1996):

Papers	Tutorials
Mandayam Srivas	Albert Camilleri
Re: FMCAD '96	Re: FMCAD '96
SRI International (EL-262)	Hewlett-Packard Co. M/S 5596
333 Ravenswood Avenue	8000 Foothills Boulevard
Menlo Park, CA 94025	Roseville, CA 95747-5596
E-mail: srivas@csl.sri.com	E-mail: ac@hprpcd.rose.hp.com
Tel: +1 415-859-6136	Tel : +1 916 785 8488
Fax: +1 415-859-2844	Fax : +1 916 785 3096

### Theorem Proving in Higher-Order Logics

The 1996 International Conference on Theorem Proving in Higher-Order Logics will be held on August 27–30, 1996, in Turku, Finland. Authors are invited to submit papers on all aspects of theorem proving, particularly those relating to higher-order logics or to proof systems based on secure mechanizations of logic. These include advances in theorem-proving technology, proof automation and decision procedures, applications of mechanized theorem proving, development and extension of higher-order logics, and novel industrial applications of theorem provers.

Submissions are invited in two categories: **A** - full research paper, and **B** - informal progress report. Category A papers are due March 15, 1996; these will be refereed and, if accepted, published in the conference proceedings. Category B papers will be distributed in an informal proceedings at the workshop. All papers are due April 14, 1996.

E-mail submissions to [orgcom@abo.fi](mailto:orgcom@abo.fi) (in PostScript form) are encouraged. Paper copies may be sent to the Department of Computer Science, Abo Akademi University, Lemminkaisenkatu 14a, FIN-20520 Turku, Finland.

### FroCoS'96

The first international workshop on Frontiers of Combining Systems will be held on March 26–29, 1996, in Munich, Germany. In various areas of logic, computation, language processing, and artificial intelligence there is an obvious need for using specialized formalisms and inference mechanisms for special tasks. In order to be usable in practice, these specialized systems must be combined, and they must be integrated into general-purpose systems. The development of general techniques for the combination and integration of special systems has been initiated in many areas, and the workshop Frontiers of Combining Systems intends to offer a common forum for these research activities.

Topics of the workshop are

- combination of logics (e.g., modal logics, logics in AI)
- combination of constraint solving techniques
- integration of equational and other theories into deductive systems
- combination of term rewriting systems

- integration of data structures into CLP formalisms and deduction processes
- hybrid systems in computational linguistics, knowledge representation, natural language semantics, and human computer interaction
- logic modeling of multi-agent systems.

Invited speakers include A. Colmerauer, D. Gabbay, U. Glaesser, and M. Stickel. For further information, see <http://www.cis.uni-muenchen.de/hot/frocos96.html> or contact K. U. Schulz, CIS, University of Munich, Wagnmuellerstr. 23, D-80538 Muenchen, Germany; e-mail: [schulz@cis.uni-muenchen.de](mailto:schulz@cis.uni-muenchen.de).

## An Automated Natural Deduction Proof of the Formalization of the Halting Problem

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In [5] we suggested using the following three formulas as premises of the halting problem, the first two of which are from [1,2,3]. Let  $P_i$  stand for the  $i$ th premise,  $i = 1, 2, 3$ . Then the formalization of the halting problem is as follows.

The English statement for the halting problem is given in [1,2,3]. The notation is as follows:

$Ax$  :  $x$  is an algorithm

$Cx$  :  $x$  is a computer program in some programming language

$Dxyz$  :  $x$  is able to decide whether  $y$  halts given input  $z$

$H_2xy$  :  $x$  halts on given input  $y$

$H_3xyz$  :  $x$  halts on given input the pair  $\langle y, z \rangle$

$Oxy$  :  $x$  outputs  $y$

$P_1$  (for premise 1):

$$\exists x[Ax \wedge \forall y[Cy \rightarrow \forall zDxyz]] \rightarrow \exists w[Cw \wedge \forall y[Cy \rightarrow \forall zDwyz]]$$

$P_2$  (for premise 2):

$$\forall w[[Cw \wedge \forall u[Cu \rightarrow \forall vDwuv]] \rightarrow$$

$$\forall y\forall z[[[Cy \wedge H_2yz] \rightarrow [H_3wyz \wedge Owg]] \wedge [[Cy \wedge \sim H_2yz] \rightarrow [H_3wyz \wedge Obw]]]]$$

$P_3$  (for premise 3):

$$\forall w[Cw \wedge \forall y\forall z[[Cy \wedge H_2yz \rightarrow H_3wyz \wedge Owg] \wedge [Cy \wedge \sim H_2yz \rightarrow H_3wyz \wedge Obw]]$$

$$\rightarrow \exists v[Cv \wedge \forall y[[Cy \wedge H_3wyy \wedge Owg \rightarrow \sim H_2vy] \wedge [Cy \wedge H_3wyy \wedge Obw \rightarrow H_2vy \wedge Obv]]]]$$

The conclusion is that an algorithm to solve the halting problem does not exist.

That is,  $\sim \exists x[Ax \wedge \forall y[Cy \rightarrow \forall zDxyz]]$ .

The problem is to prove that  $P_1 \wedge P_2 \wedge P_3 \rightarrow \sim \exists x[Ax \wedge \forall y[Cy \rightarrow \forall zDxyz]]$  is valid.

We report here a mechanical proof, in natural deduction (ND) style, of the new formalization above. The proof was found automatically by our ANDP system. It is a direct proof and consists of 74 natural deduction steps. Clearly the ND proof is readable.

In [7] Uwe Egly and Thomas Rath reported the first mechanical resolution proof of the new formalization of the halting problem. In [4] we presented a mechanical proof in natural deduction style of Burkholder's formalization of the halting problem. However, our ANDP failed to find a mechanical proof of the new formalization; we were able to give only a hand-crafted ND proof of the formalization [5]. Why did ANDP fail to prove it? After many experiments, we found that one of the reasons was that the rule CASES was applied limitlessly. If the rule CASES is applied to a disjunction, two disjuncts of it will be used as new hypotheses. We conjectured that it might produce new constants from the new hypotheses, hence many new Herbrand terms and irrelevant and redundant formulas. To address that problem, we developed the following strategies:

1. The rule CASES is first applied to premises.
2. The rule CASES is then applied to the disjunctions from which it will not produce new constants.
3. The rule CASES is then applied to short formulas.

The strategies will not affect the completeness. Numerous experiments proved that the strategies were general. Using the strategies, ANDP not only found a mechanical proof in natural deduction style of the new formalization of the halting problem but also produced the small search spaces for Burkholder's original formalization of the halting problem in [1, 2, 3] and Pelletier's 75-problems [6].

## Acknowledgment

The project was supported by NSFC.

## Appendix: The Mechanical Proof of the Formulation of the Halting Problem

We use  $(\exists x)$ ,  $(\forall x)$  to stand for existential quantifier and universal quantifier respectively.

- |    |  |                 |
|----|--|-----------------|
| 1. | P1 & P2 & P3   | ASSUMED-PREMISE |
| 2. | $(\exists x)[Ax \ \& \ (\forall y)[Cy \ \rightarrow \ (\forall z)Dxyz]]$   |                 |
|    | $\rightarrow (\exists w)[Cw \ \& \ (\forall y)[Cy \ \rightarrow \ (\forall z)Dwyz]]$                               | SIMP 1          |
| 3. | $(\forall w)[Cw \ \& \ (\forall u)[Cu \ \rightarrow \ (\forall v)Dwuv]$  |                 |
|    | $\rightarrow (\forall y)(\forall z)[[Cy \ \& \ H2yz \ \rightarrow \ H3wyz \ \& \ Owg] \ \& \ [Cy \ \& \ \sim H2yz$ |                 |
|    | $\rightarrow H3wyz \ \& \ Owb]]]$  | SIMP 1          |

4.  $(Aw)[Cw \ \& \ (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3wyz \ \& \ Owg] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3wyz \ \& \ Owb]] \rightarrow (Ev)[Cv \ \& \ (Ay)[[[Cy \ \& \ H3wyy] \ \& \ Owg \ \rightarrow \ \sim H2vy] \ \& \ [[Cy \ \& \ H3wyy] \ \& \ Owb \ \rightarrow \ H2vy \ \& \ Ovb]]]]$  SIMP 1
5.  $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]$  CASE 2
6.  $(Ew)[Cw \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dwyz]$  CASE 2
7.  $Ca1 \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Da1yz]$  HYPO 6
8.  $Ca1$  SIMP 7
9.  $(Ay)[Cy \ \rightarrow \ (Az)Da1yz]$  SIMP 7
10.  $Ca1 \ \& \ (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]] \rightarrow (Ev)[Cv \ \& \ (Ay)[[[Cy \ \& \ H3a1yy] \ \& \ Oa1g \ \rightarrow \ \sim H2vy] \ \& \ [[Cy \ \& \ H3a1yy] \ \& \ Oa1b \ \rightarrow \ H2vy \ \& \ Ovb]]]$  US (a1 w) 4
11.  $\sim Ca1 \ \vee \ [ \sim (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]] \ \vee \ (Ev)[Cv \ \& \ (Ay)[[[Cy \ \& \ H3a1yy] \ \& \ Oa1g \ \rightarrow \ \sim H2vy] \ \& \ [[Cy \ \& \ H3a1yy] \ \& \ Oa1b \ \rightarrow \ H2vy \ \& \ Ovb]]]]$  IMPLICATION 10
12.  $\sim (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]] \ \vee \ (Ev)[Cv \ \& \ (Ay)[[[Cy \ \& \ H3a1yy] \ \& \ Oa1g \ \rightarrow \ \sim H2vy] \ \& \ [[Cy \ \& \ H3a1yy] \ \& \ Oa1b \ \rightarrow \ H2vy \ \& \ Ovb]]]$  LDS 11 8
13.  $Ca1 \ \& \ (Au)[Cu \ \rightarrow \ (Av)Da1uv] \rightarrow (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]]$  US (a1 w) 3
14.  $\sim Ca1 \ \vee \ [ \sim (Au)[Cu \ \rightarrow \ (Av)Da1uv] \ \vee \ (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]]]$  IMPLICATION 13
15.  $\sim (Au)[Cu \ \rightarrow \ (Av)Da1uv] \ \vee \ (Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]]$  LDS 14 8
16.  $(Ay)(Az)[[Cy \ \& \ H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1g] \ \& \ [Cy \ \& \ \sim H2yz \ \rightarrow \ H3a1yz \ \& \ Oa1b]]$  LDS 15 9
17.  $(Ev)[Cv \ \& \ (Ay)[[[Cy \ \& \ H3a1yy] \ \& \ Oa1g \ \rightarrow \ \sim H2vy] \ \& \ [[Cy \ \& \ H3a1yy] \ \& \ Oa1b \ \rightarrow \ H2vy \ \& \ Ovb]]]$  LDS 12 16
18.  $Ca2 \ \& \ (Ay)[[[Cy \ \& \ H3a1yy] \ \& \ Oa1g \ \rightarrow \ \sim H2a2y] \ \& \ [[Cy \ \& \ H3a1yy] \ \& \ Oa1b \ \rightarrow \ H2a2y \ \& \ Oa2b]]$  HYPO 17
19.  $Ca2$  SIMP 18
20.  $(Ay)[[[Cy \ \& \ H3a1yy] \ \& \ Oa1g \ \rightarrow \ \sim H2a2y] \ \& \ [[Cy \ \& \ H3a1yy] \ \& \ Oa1b \ \rightarrow \ H2a2y \ \& \ Oa2b]]$  SIMP 18
21.  $[[Ca1 \ \& \ H3a1a1a1] \ \& \ Oa1g \ \rightarrow \ \sim H2a2a1] \ \& \ [[Ca1 \ \& \ H3a1a1a1] \ \& \ Oa1b \ \rightarrow \ H2a2a1 \ \& \ Oa2b]$  US (a1 y) 20
22.  $[Ca1 \ \& \ H3a1a1a1] \ \& \ Oa1g \ \rightarrow \ \sim H2a2a1$  SIMP 21
23.  $[Ca1 \ \& \ H3a1a1a1] \ \& \ Oa1b \ \rightarrow \ H2a2a1 \ \& \ Oa2b$  SIMP 21

24.	$\sim Ca1 \vee [ [\sim H3a1a1a1 \vee \sim 0a1b] \vee H2a2a1 \ \& \ 0a2b]$	IMPLICATION 23
25.	$[\sim H3a1a1a1 \vee \sim 0a1b] \vee H2a2a1 \ \& \ 0a2b$	LDS 24 8
26.	$\sim Ca1 \vee [ [\sim H3a1a1a1 \vee \sim 0a1g] \vee \sim H2a2a1]$	IMPLICATION 22
27.	$[\sim H3a1a1a1 \vee \sim 0a1g] \vee \sim H2a2a1$	LDS 26 8
28.	$[[\sim H3a1a1a1 \vee \sim 0a1b] \vee H2a2a1] \ \& \ [ [\sim H3a1a1a1 \vee \sim 0a1b] \vee 0a2b]$	DISTRIBUTIVE-LAW 25
29.	$[\sim H3a1a1a1 \vee \sim 0a1b] \vee H2a2a1$	SIMP 28
30.	$\sim H3a1a1a1 \vee \sim 0a1g$	CASE 27
31.	$\sim H2a2a1$	CASE 27
32.	$\sim H3a1a1a1 \vee \sim 0a1b$	RDS 29 31
33.	$(Az)[[Ca2 \ \& \ H2a2z \ \rightarrow \ H3a1a2z \ \& \ 0a1g] \ \& \ [Ca2 \ \& \ \sim H2a2z \ \rightarrow \ H3a1a2z \ \& \ 0a1b]]$	US (a2 y) 16
34.	$[Ca2 \ \& \ H2a2a1 \ \rightarrow \ H3a1a2a1 \ \& \ 0a1g] \ \& \ [Ca2 \ \& \ \sim H2a2a1 \ \rightarrow \ H3a1a2a1 \ \& \ 0a1b]$	US (a1 z) 33
35.	$Ca2 \ \& \ H2a2a1 \ \rightarrow \ H3a1a2a1 \ \& \ 0a1g$	SIMP 34
36.	$Ca2 \ \& \ \sim H2a2a1 \ \rightarrow \ H3a1a2a1 \ \& \ 0a1b$	SIMP 34
37.	$\sim Ca2 \vee [H2a2a1 \vee H3a1a2a1 \ \& \ 0a1b]$	IMPLICATION 36
38.	$H2a2a1 \vee H3a1a2a1 \ \& \ 0a1b$	LDS 37 19
39.	$H3a1a2a1 \ \& \ 0a1b$	LDS 38 31
40.	$0a1b$	SIMP 39
41.	$\sim H3a1a1a1$	RDS 32 40
42.	$\sim Ca2 \vee [ \sim H2a2a1 \vee H3a1a2a1 \ \& \ 0a1g]$	IMPLICATION 35
43.	$\sim H2a2a1 \vee H3a1a2a1 \ \& \ 0a1g$	LDS 42 19
44.	$[ \sim H2a2a1 \vee H3a1a2a1] \ \& \ [ \sim H2a2a1 \vee 0a1g]$	DISTRIBUTIVE-LAW 43
45.	$\sim H2a2a1 \vee 0a1g$	SIMP 44
46.	$(Az)[[Ca1 \ \& \ H2a1z \ \rightarrow \ H3a1a1z \ \& \ 0a1g] \ \& \ [Ca1 \ \& \ \sim H2a1z \ \rightarrow \ H3a1a1z \ \& \ 0a1b]]$	US (a1 y) 16
47.	$[Ca1 \ \& \ H2a1a1 \ \rightarrow \ H3a1a1a1 \ \& \ 0a1g] \ \& \ [Ca1 \ \& \ \sim H2a1a1 \ \rightarrow \ H3a1a1a1 \ \& \ 0a1b]$	US (a1 z) 46
48.	$Ca1 \ \& \ H2a1a1 \ \rightarrow \ H3a1a1a1 \ \& \ 0a1g$	SIMP 47
49.	$Ca1 \ \& \ \sim H2a1a1 \ \rightarrow \ H3a1a1a1 \ \& \ 0a1b$	SIMP 47
50.	$\sim Ca1 \vee [H2a1a1 \vee H3a1a1a1 \ \& \ 0a1b]$	IMPLICATION 49
51.	$H2a1a1 \vee H3a1a1a1 \ \& \ 0a1b$	LDS 50 8
52.	$\sim Ca1 \vee [ \sim H2a1a1 \vee H3a1a1a1 \ \& \ 0a1g]$	IMPLICATION 48
53.	$\sim H2a1a1 \vee H3a1a1a1 \ \& \ 0a1g$	LDS 52 8
54.	$[H2a1a1 \vee H3a1a1a1] \ \& \ [H2a1a1 \vee 0a1b]$	DISTRIBUTIVE-LAW 51
55.	$H2a1a1 \vee H3a1a1a1$	SIMP 54
56.	$H2a1a1 \vee 0a1b$	SIMP 54
57.	$H2a1a1$	RDS 55 41
58.	$H3a1a1a1 \ \& \ 0a1g$	LDS 53 57
59.	$H3a1a1a1$	SIMP 58
60.	$\sim H2a1a1$	RDS 30 53

61. $0a1b$	LDS 56 60
62. $H3a1a1a1$	LDS 55 60
63. $\sim 0a1g$	LDS 30 62
64. $\sim H2a2a1$	RDS 45 63
65. $\sim H3a1a1a1 \vee \sim 0a1b$	RDS 29 64
66. $\sim 0a1b$	LDS 65 62
67. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	$\sim$ -ELIMINATION 59 41
68. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	$\sim$ -ELIMINATION 61 66
69. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	CASES 27 68 67
70. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	EE 17 69
71. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	EE 6 70
72. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	SAME 5
73. $\sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	CASES 2 72 71
74. $P1 \ \& \ P2 \ \& \ P3 \ \rightarrow \ \sim (Ex)[Ax \ \& \ (Ay)[Cy \ \rightarrow \ (Az)Dxyz]]$	CP 73

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